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To capture the data, the researchers designed an automated system consisting of an industrial robotic arm with precise control, a 3D motion-tracking system, depth and traditional cameras, and software that stitches everything together. The arm pushes around modular objects that can be adjusted for

weight, shape, and mass distribution.

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Fundamentals Of Object Tracking

Fundamentals of Object Tracking tells you how. Starting with the generic object-tracking problem, it outlines the generic Bayesian solution. It then shows systematically how to formulate the major tracking problems - maneuvering, multiobject, clutter, out-of-sequence sensors - within this Bayesian framework and how to derive the standard tracking solutions.

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Object/target tracking refers to the problem of using sensor measurements to determine the location, path and characteristics of objects of interest. A sensor can be any measuring device, such as radar, sonar, lidar, camera, infrared sensor, microphone, ultrasound or any other sensor that can be used to collect information about objects in the environment.

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Simple object tracking with OpenCV - PyImageSearch

Object tracking is the process of: Taking an initial set of object detections (such as an input set of bounding box coordinates) Creating a unique ID for each of the initial detections And then tracking each of the objects as they move around frames in a video, maintaining the assignment of unique IDs

Introduction to object tracking (Chapter

1) - Fundamentals ...

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