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Based on the highly successful classic, Robot Dynamics and Control, by Spong and Vidyasagar (Wiley, 1989), Robot Modeling and Control offers a thoroughly up-to-date, self-contained introduction to the field. The text presents basic and advanced material in a style that is at once readable and mathematically rigorous. Key

Features

Robot Modeling and Control

Robot Modeling and Control introduces the fundamentals of robot modeling and control and provides background material on terminology, linear algebra, dynamical systems and stability theory, followed by detailed coverage of forward and in-verse kinematics, Jacobians, Lagrangian dynamics, motion planning, robust and adaptive motion and force control, and com-puter vision. Both basic and advanced material is presented in a style that is readable and mathematically rigorous.

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1.1 Mathematical Modeling of Robots 3 1.1.1 Symbolic Representation of Robots 3
1.1.2 The Configuration Space 4 1.1.3 The State Space 5 1.1.4 The Workspace 5
1.2 Robots as Mechanical Devices 5 ... degree of autonomy, usually under computer control, has at some point been called a robot. In this text the term robot will mean a computer controlled

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